$$\begin{array}{ll} \mathbf{b} & A^{-1} = \frac{1}{ad-bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix} \\ & = \frac{1}{3 \times (-4) - 2 \times 1} \begin{bmatrix} -4 & -1 \\ -2 & 3 \end{bmatrix} \\ & = -\frac{1}{14} \begin{bmatrix} -4 & -1 \\ -2 & 3 \end{bmatrix} \\ & = \begin{bmatrix} \frac{2}{7} & \frac{1}{14} \\ \frac{1}{7} & -\frac{3}{14} \end{bmatrix}. \end{array}$$

$$A^{-1} = rac{1}{ad-bc}igg[egin{array}{ccc} d & -b \ -c & a \ \end{array}igg] \ = rac{1}{0 imes 4-3 imes (-2)}igg[egin{array}{ccc} 4 & -3 \ 2 & 0 \ \end{array}igg] \ = igg[rac{2}{3} & -rac{1}{2} \ rac{1}{3} & 0 \ \end{array}igg]$$

$$A^{-1} = rac{1}{ad-bc}igg[egin{array}{ccc} d & -b \ -c & a \ \end{array}igg] \ = rac{1}{(-1) imes 5 - 3 imes (-4)}igg[egin{array}{ccc} 5 & -3 \ 4 & -1 \ \end{array}igg] \ = rac{1}{7}igg[egin{array}{ccc} 5 & -3 \ 4 & -1 \ \end{array}igg] \ = igg[egin{array}{ccc} rac{5}{7} & -rac{3}{7} \ rac{4}{7} & -rac{1}{7} \ \end{array}igg]$$

2 a Since the matrix of this linear transformation is
$$A=egin{bmatrix} 5 & -2 \ 2 & -1 \end{bmatrix},$$

the inverse transformation will have matrix

$$egin{aligned} A^{-1} &= rac{1}{ad-bc}igg[egin{array}{ccc} d & -b \ -c & a \ \end{array} igg] \ &= rac{1}{5 imes(-1)-(-2) imes 2}igg[egin{array}{ccc} -1 & 2 \ -2 & 5 \ \end{array} igg] \ &= rac{1}{-1}igg[egin{array}{cccc} -1 & 2 \ -2 & 5 \ \end{array} igg] \end{aligned}$$

Therefore the rule of the inverse transformation is (x,y) o (x-2y,2x-5y)

b Since the matrix of this linear transformation is

$$A = \begin{bmatrix} 1 & -1 \\ 1 & 0 \end{bmatrix}$$
,

the inverse transformation will have matrix

$$A^{-1} = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$
$$= \frac{1}{1 \times 0 - (-1) \times 1} \begin{bmatrix} 0 & 1 \\ -1 & 1 \end{bmatrix}$$
$$= \begin{bmatrix} 0 & 1 \\ -1 & 1 \end{bmatrix}$$

Therefore, the rule of the inverse transformation is (x,y) o (y,-x+y).

We need to solve the following equation for X.

$$\begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix} X = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$
$$X = \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix}^{-1} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$
$$= \begin{bmatrix} 1 & -2 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$
$$= \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

Therefore, $(-1,1) \rightarrow (1,1)$.

b We need to solve the following equation for *X*.

$$\begin{bmatrix} 4 & 3 \\ 2 & 2 \end{bmatrix} X = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$X = \begin{bmatrix} 4 & 3 \\ 2 & 2 \end{bmatrix}^{-1} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$= \frac{1}{2} \begin{bmatrix} 2 & -3 \\ -2 & 4 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$= \frac{1}{2} \begin{bmatrix} -1 \\ 2 \end{bmatrix}$$

$$= \begin{bmatrix} -\frac{1}{2} \\ 1 \end{bmatrix}$$

Therefore $(-\frac{1}{2},1) o (1,1)$.

We need to find a matrix A such that

$$A \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \end{bmatrix} \text{ and } A \begin{bmatrix} 2 \\ 3 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}.$$

This can be written as a single equation, which we then solve to give

$$A \begin{bmatrix} 1 & 2 \\ 2 & 3 \end{bmatrix} = \begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix}$$
$$A = \begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 2 & 3 \end{bmatrix}^{-1}$$
$$= \begin{bmatrix} -4 & 3 \\ -1 & 1 \end{bmatrix}.$$

This can be solved in one step by solving the following equation for X.

$$\begin{bmatrix} 1 & -1 \\ 2 & -1 \end{bmatrix} X = \begin{bmatrix} 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \end{bmatrix}$$
$$X = \begin{bmatrix} 1 & -1 \\ 2 & -1 \end{bmatrix}^{-1} \begin{bmatrix} 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \end{bmatrix}$$
$$= \begin{bmatrix} -1 & 1 \\ -2 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \end{bmatrix}$$
$$= \begin{bmatrix} 0 & -1 & 1 & 0 \\ 0 & -2 & 1 & -1 \end{bmatrix}$$

The vertices are then given by the columns of matrix X. These are (0,0),(-1,-2),(1,1) and (0,-1).

The dilation matrix is

$$A = \left[egin{array}{cc} k & 0 \ 0 & 1 \end{array}
ight].$$

The inverse transformation will have matrix

$$A^{-1} = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

$$= \frac{1}{k \times 1 - 0 \times 0} \begin{bmatrix} 1 & -0 \\ -0 & k \end{bmatrix}$$

$$= \frac{1}{k} \begin{bmatrix} 1 & 0 \\ 0 & k \end{bmatrix}$$

$$= \begin{bmatrix} \frac{1}{k} & 0 \\ 0 & 1 \end{bmatrix}.$$

This matrix will dilate each point from the y-axis by a factor of $\frac{1}{h}$.

7 a The shear matrix is

$$A = \begin{bmatrix} 1 & k \\ 0 & 1 \end{bmatrix}$$
.

The inverse transformation will have matrix

$$A^{-1} = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

$$= \frac{1}{1 \times 1 - k \times 0} \begin{bmatrix} 1 & -k \\ -0 & 1 \end{bmatrix}$$

$$= \frac{1}{1} \begin{bmatrix} 1 & -k \\ 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & -k \\ 0 & 1 \end{bmatrix}.$$

This matrix will shear each point from the x-direction by a factor of -k.

The reflection matrix is

$$A = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$
.

The inverse transformation will have matrix
$$A^{-1} = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

$$= \frac{1}{1 \times (-1) - 0 \times 0} \begin{bmatrix} -1 & -0 \\ -0 & 1 \end{bmatrix}$$

$$= -1 \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$
$$= A.$$

This is expected, since two reflections in the same axis will return the point (x, y) to its original position.

9 a The reflection matrix is

$$\begin{bmatrix} \cos 2\theta & \sin 2\theta \\ \sin 2\theta & -\cos 2\theta \end{bmatrix}.$$

b The inverse transformation will have matrix

$$A^{-1} = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

$$= \frac{1}{-\cos^2 \theta - \sin^2 \theta} \begin{bmatrix} -\cos 2\theta & -\sin 2\theta \\ -\sin 2\theta & \cos 2\theta \end{bmatrix}$$

$$= \frac{1}{-1} \begin{bmatrix} -\cos 2\theta & -\sin 2\theta \\ -\sin 2\theta & \cos 2\theta \end{bmatrix}$$

$$= \begin{bmatrix} \cos 2\theta & \sin 2\theta \\ \sin 2\theta & -\cos 2\theta \end{bmatrix}$$

$$= A.$$

This is expected, since two reflections in the same axis will return the point (x, y) to its original position.